# Multivariate distributions and measures of dependence between random variables* 

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## 1. Random variables

1.1 In general, economic theory specifies exact relations between economic variables. Even a superficial examination of economic data indicates it is not (almost never) possible to find such relationships in actual data. Instead, we have relations of the form:

$$
C_{t}=\alpha+\beta Y_{t}+\varepsilon_{t}
$$

where $\varepsilon_{t}$ can be interpreted as a "random variable".
1.2 Definition $A$ random variable (r.v.) $X$ is a variable whose behavior can be described by a "probability law". If $X$ takes its values in the real numbers, the probability law of $X$ can be described by a "distribution function":

$$
F_{X}(x)=\mathrm{P}[X \leq x]
$$

1.3 If $X$ is continuous, there is a "density function" $f_{X}(x)$ such that

$$
F_{X}(x)=\int_{-\infty}^{x} f_{X}(x) d x
$$

The mean and variance of $X$ are given by:

$$
\begin{array}{cc}
\mu_{X}=\mathrm{E}(X)=\int_{-\infty}^{+\infty} x d F_{X}(x) & \text { (general case) } \\
=\int_{-\infty}^{+\infty} x f_{X}(x) d x & \text { (continuous case) } \\
\mathrm{V}(X)=\sigma_{X}^{2}=\mathrm{E}\left[\left(X-\mu_{X}\right)^{2}\right]=\int_{-\infty}^{+\infty}\left(x-\mu_{X}\right)^{2} d F_{X}(x) \\
=\int_{-\infty}^{+\infty}\left(x-\mu_{X}\right)^{2} F_{X}(x) d x & \text { (general case) } \\
=\mathrm{E}\left(X^{2}\right)-[\mathrm{E}(X)]^{2} & \text { (continuous case) }
\end{array}
$$

1.4 It is easy to characterize relations between two non-random variables $x$ and $y$ :

$$
g(x, y)=0
$$

or (in certain cases)

$$
y=f(x) .
$$

How does one characterize the links or relations between random variables? The behavior of a pair $(X, Y)^{\prime}$ is described by a joint distribution function:

$$
F(x, y)=\mathrm{P}[X \leq x, Y \leq y]
$$

$$
=\int_{-\infty}^{y} \int_{-\infty}^{x} f(x, y) d x d y \quad \text { (continuous case.) }
$$

We call $f(x, y)$ the joint density function of $(X, Y)^{\prime}$. More generally, if we consider $k$ r.v.'s $X_{1}, X_{2}, \ldots, X_{k}$, their behavior can be described through a $k$-dimensional distribution function:

$$
\begin{aligned}
& \quad F\left(x_{1}, x_{2}, \ldots, x_{k}\right)=\mathrm{P}\left[X_{1} \leq x_{1}, X_{2} \leq x_{2}, \ldots, X_{k} \leq x_{k}\right] \\
& =\int_{-\infty}^{x_{k}} \cdots \int_{-\infty}^{x_{2}} \int_{-\infty}^{x_{1}} f\left(x_{1}, x_{2}, \ldots, x_{k}\right) d x_{1} d x_{2} \cdots d x_{k}
\end{aligned}
$$

where $f\left(x_{1}, x_{2}, \ldots, x_{k}\right)$ is the joint density function of $X_{1}, X_{2}, \ldots, X_{k}$.

## 2. Covariances and correlations

We often wish to have a simple measure of association between two random variables $X$ and $Y$. The notions of "covariance" and "correlation" provide such measures of association. Let $X$ and $Y$ be two r.v.'s with means $\mu_{X}$ and $\mu_{Y}$ and finite variances $\sigma_{X}^{2}$ and $\sigma_{Y}^{2}$. Below a.s. means "almost surely" (with probability 1 ).
2.1 Definition The covariance between $X$ and $Y$ is defined by

$$
\mathrm{C}(X, Y) \equiv \sigma_{X Y} \equiv \mathrm{E}\left[\left(X-\mu_{X}\right)\left(Y-\mu_{Y}\right)\right]
$$

2.2 Definition Suppose $\sigma_{X}^{2}>0$ and $\sigma_{Y}^{2}>0$. Then the correlation between $X$ and $Y$ is defined by

$$
\rho(X, Y) \equiv \rho_{X Y} \equiv \sigma_{X Y} / \sigma_{X} \sigma_{Y}
$$

When $\sigma_{X}^{2}=0$ or $\sigma_{Y}^{2}=0$, we set $\rho_{X Y}=0$.
2.3 Theorem The covariance and correlation between $X$ and $Y$ satisfy the following properties:
(a) $\sigma_{X Y}=\mathrm{E}(X Y)-\mathrm{E}(X) \mathrm{E}(Y)$;
(b) $\sigma_{X Y}=\sigma_{Y X}, \rho_{X Y}=\rho_{Y X}$;
(c) $\sigma_{X X}=\sigma_{X}^{2}, \rho_{X X}=1$;
(d) $\sigma_{X Y}^{2} \leq \sigma_{X}^{2} \sigma_{Y}^{2}$;
(Cauchy-Schwarz inequality)
(e) $-1 \leq \rho_{X Y} \leq 1$;
(f) $X$ and $Y$ are independent $\Rightarrow \sigma_{X Y}=0 \Rightarrow \rho_{X Y}=0$;
(g) if $\sigma_{X}^{2} \neq 0$ and $\sigma_{Y}^{2} \neq 0$,

$$
\rho_{X Y}^{2}=1 \Leftrightarrow[\exists \text { two constants } a \text { and } b \text { such that } a \neq 0 \text { and } Y=a X+b \text { a.s. }]
$$

## Proof (a)

$$
\begin{aligned}
\sigma_{X Y} & =\mathrm{E}\left[\left(X-\mu_{X}\right)\left(Y-\mu_{Y}\right)\right] \\
& =\mathrm{E}\left[X Y-\mu_{X} Y-X \mu_{Y}+\mu_{X} \mu_{Y}\right] \\
& =\mathrm{E}(X Y)-\mu_{X} \mathrm{E}(Y)-\mathrm{E}(X) \mu_{Y}+\mu_{X} \mu_{Y} \\
& =\mathrm{E}(X Y)-\mu_{X} \mu_{Y}-\mu_{X} \mu_{Y}+\mu_{X} \mu_{y} \\
& =\mathrm{E}(X Y)-\mathrm{E}(X) \mathrm{E}(Y)
\end{aligned}
$$

(b) et (c) are immediate. To get (d), we observe that

$$
\begin{gathered}
\mathrm{E}\left\{\left[Y-\mu_{Y}-\lambda\left(X-\mu_{X}\right)\right]^{2}\right\}=\mathrm{E}\left\{\left[\left(Y-\mu_{Y}\right)-\lambda\left(X-\mu_{X}\right)\right]^{2}\right\} \\
\mathrm{E} \mathrm{E}\left\{\left(Y-\mu_{Y}\right)^{2}-2 \lambda\left(X-\mu_{X}\right)\left(Y-\mu_{Y}\right)+\lambda^{2}\left(X-\mu_{X}\right)^{2}\right\} \\
=\sigma_{Y}^{2}-2 \lambda \sigma_{X Y}+\lambda^{2} \sigma_{X}^{2} \geq 0
\end{gathered}
$$

for any arbitrary constant $\lambda$. In other words, the second-order polynomial $g(\lambda)=\sigma_{Y}^{2}-2 \lambda \sigma_{X Y}+$ $\lambda^{2} \sigma_{X}^{2}$ cannot take negative values. This can happen only if the equation

$$
\begin{equation*}
\lambda^{2} \sigma_{X}^{2}-2 \lambda \sigma_{X Y}+\sigma_{Y}^{2}=0 \tag{2.1}
\end{equation*}
$$

does not have two distinct real roots, i.e. the roots are either complex or identical. The roots of equation (2.1). are given by

$$
\lambda=\frac{2 \sigma_{X Y} \pm \sqrt{4 \sigma_{X Y}^{2}-4 \sigma_{X}^{2} \sigma_{Y}^{2}}}{2 \sigma_{X}^{2}}=\frac{\sigma_{X Y} \pm \sqrt{\sigma_{X Y}^{2}-\sigma_{X}^{2} \sigma_{Y}^{2}}}{\sigma_{X}^{2}}
$$

Distinct real roots are excluded when $\sigma_{X Y}^{2}-\sigma_{X}^{2} \sigma_{Y}^{2} \leq 0$, hence

$$
\sigma_{X Y}^{2} \leq \sigma_{X}^{2} \sigma_{Y}^{2}
$$

(e)

$$
\begin{aligned}
\sigma_{X Y}^{2} \leq \sigma_{X}^{2} \sigma_{Y}^{2} & \Rightarrow-\sigma_{X} \sigma_{Y} \leq \sigma_{X Y} \leq \sigma_{X} \sigma_{Y} \\
& \Rightarrow-1 \leq \rho_{X Y} \leq 1
\end{aligned}
$$

(f)

$$
\begin{aligned}
\sigma_{X Y} & =\mathrm{E}\left\{\left(X-\mu_{X}\right)\left(Y-\mu_{Y}\right)\right\}=\mathrm{E}\left(X-\mu_{X}\right) \mathrm{E}\left(Y-\mu_{Y}\right) \\
& =\left[\mathrm{E}(X)-\mu_{X}\right]\left[\mathrm{E}(Y)-\mu_{Y}\right]=0, \\
\rho_{X Y} & =\sigma_{X Y} / \sigma_{X} \sigma_{Y}=0 .
\end{aligned}
$$

Note the reverse implication does not hold in general, i.e.,

$$
\rho_{X Y}=0 \neq>X \text { and } Y \text { are independent }
$$

(g) 1) Necessity of the condition. If $Y=a X+b$, then

$$
\mathrm{E}(Y)=a \mathrm{E}(X)+b=a \mu_{X}+b, \sigma_{Y}^{2}=a^{2} \sigma_{X}^{2},
$$

and

$$
\sigma_{X Y}=\mathrm{E}\left[\left(Y-\mu_{Y}\right)\left(X-\mu_{X}\right)\right]=\mathrm{E}\left[a\left(X-\mu_{X}\right)\left(X-\mu_{X}\right)\right]=a \sigma_{X}^{2} .
$$

Consequently,

$$
\rho_{X Y}^{2}=\frac{a^{2} \sigma_{X}^{4}}{a^{2} \sigma_{X}^{2} \sigma_{X}^{2}}=1 .
$$

2) Sufficiency of the condition. If $\rho_{X Y}^{2}=1$, then

$$
\sigma_{X Y}^{2}-\sigma_{X}^{2} \sigma_{Y}^{2}=0
$$

In this case, the equation

$$
\mathrm{E}\left\{\left[\left(Y-\mu_{Y}\right)-\lambda\left(X-\mu_{X}\right)\right]^{2}\right\}=\sigma_{Y}^{2}-2 \lambda \sigma_{X Y}+\lambda^{2} \sigma_{X}^{2}=0
$$

has one and only one root

$$
\lambda=\frac{2 \sigma_{X Y}}{2 \sigma_{X}^{2}}=\sigma_{X Y} / \sigma_{X}^{2},
$$

so that

$$
\mathrm{E}\left\{\left[\left(Y \sigma_{Y}^{2}-\mu_{Y}\right)-\frac{\sigma_{X Y}}{\sigma_{X}^{2}}\left(X-\mu_{X}\right)\right]^{2}\right\}=0
$$

and

$$
\mathrm{P}\left[\left(Y-\mu_{Y}\right)-\frac{\sigma_{X Y}}{\sigma_{X}^{2}}\left(X-\mu_{X}\right)=0\right]=\mathrm{P}\left[Y=\frac{\sigma_{X Y}}{\sigma_{X}^{2}} X+\left(\mu_{Y}-\frac{\sigma_{X Y}}{\sigma_{X}^{2}} \mu_{X}\right)\right]=1
$$

We can thus write:

$$
Y=a X+b \text { with probability } 1
$$

where $a=\sigma_{X Y} / \sigma_{X}^{2}$ and $b=\mu_{Y}-\frac{\sigma_{X Y}}{\sigma_{y}^{2}} \mu_{X}$.

## 3. Alternative interpretations of covariances and correlations

Highly correlated random variables tend to be "close". This feature can be explicated in different ways:

1. by looking at the distribution of the difference $Y-X$;
2. by looking at the difference of two variances (polarization identity);
3. by looking at the linear regression of $Y$ on $X$;
4. through a "decoupling" representation of covariances and correlations.

### 3.1. Difference between two correlated random variables

First, we can look at the difference of two random variables $X$ and $Y$. It is easy to see that

$$
\begin{align*}
E\left[(Y-X)^{2}\right] & =E\left\{\left(\left[\left(Y-\mu_{Y}\right)-\left(X-\mu_{X}\right)\right]-\left(\mu_{Y}-\mu_{X}\right)\right)^{2}\right\} \\
& =E\left\{\left(\left[\left(Y-\mu_{Y}\right)-\left(X-\mu_{X}\right)\right]\right)^{2}\right\}+\left(\mu_{Y}-\mu_{X}\right)^{2} \\
& =\sigma_{Y}^{2}+\sigma_{X}^{2}-2 \sigma_{X Y}+\left(\mu_{Y}-\mu_{X}\right)^{2} \\
& =\sigma_{Y}^{2}+\sigma_{X}^{2}-2 \rho_{X Y} \sigma_{X} \sigma_{Y}+\left(\mu_{Y}-\mu_{X}\right)^{2} . \tag{3.1}
\end{align*}
$$

$E\left[(Y-X)^{2}\right]$ has three components: (1) a variance component $\sigma_{Y}^{2}+\sigma_{X}^{2}$; (2) a covariance component $-2 \sigma_{X Y}$; (3) a mean component $\left(\mu_{Y}-\mu_{X}\right)^{2}$. Equation (3.1) shows clearly that $E\left[(Y-X)^{2}\right]$ tends to be large, when they have very different means or variances.

Since $\left|\rho_{X Y}\right| \leq 1$, it is interesting to observe that

$$
\begin{equation*}
\left(\sigma_{Y}-\sigma_{X}\right)^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2} \leq E\left[(Y-X)^{2}\right] \leq\left(\sigma_{Y}+\sigma_{X}\right)^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2}, \tag{3.2}
\end{equation*}
$$

and

$$
\begin{gather*}
E\left[(Y-X)^{2}\right] \leq \sigma_{Y}^{2}+\sigma_{X}^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2} \leq\left(\sigma_{Y}+\sigma_{X}\right)^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2}, \text { if } \rho_{X Y} \geq 0,  \tag{3.3}\\
E\left[(Y-X)^{2}\right] \geq \sigma_{Y}^{2}+\sigma_{X}^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2} \geq\left(\sigma_{Y}-\sigma_{X}\right)^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2}, \text { if } \rho_{X Y} \leq 0,  \tag{3.4}\\
E\left[(Y-X)^{2}\right]=\sigma_{Y}^{2}+\sigma_{X}^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2}, \text { if } \rho_{X Y}=0 . \tag{3.5}
\end{gather*}
$$

$E\left[(Y-X)^{2}\right]$ reaches its minimum value when $\rho_{X Y}=1$, and its maximal value when $\rho_{X Y}=-1$ :

$$
\begin{gather*}
E\left[(Y-X)^{2}\right]=\left(\sigma_{Y}-\sigma_{X}\right)^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2}, \quad \text { if } \rho_{X Y}=1,  \tag{3.6}\\
E\left[(Y-X)^{2}\right]=\left(\sigma_{Y}+\sigma_{X}\right)^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2}, \quad \text { if } \rho_{X Y}=-1 \tag{3.7}
\end{gather*}
$$

If $\sigma_{Y}^{2}>0$, we can also write:

$$
\begin{equation*}
\left(1-\frac{\sigma_{X}}{\sigma_{Y}}\right)^{2}+\left(\frac{\mu_{Y}-\mu_{X}}{\sigma_{Y}}\right)^{2} \leq \frac{E\left[(Y-X)^{2}\right]}{\sigma_{Y}^{2}} \leq\left(1+\frac{\sigma_{X}}{\sigma_{Y}}\right)^{2}+\left(\frac{\mu_{Y}-\mu_{X}}{\sigma_{Y}}\right)^{2} . \tag{3.8}
\end{equation*}
$$

The inequalities (3.2) - (3.5) also entail similar properties for $X+Y$ :

$$
\begin{gather*}
\left(\sigma_{X}-\sigma_{Y}\right)^{2}+\left(\mu_{X}+\mu_{Y}\right)^{2} \leq E\left[(X+Y)^{2}\right] \leq\left(\sigma_{X}+\sigma_{Y}\right)^{2}+\left(\mu_{X}+\mu_{Y}\right)^{2}  \tag{3.9}\\
E\left[(X+Y)^{2}\right] \leq \sigma_{X}^{2}+\sigma_{Y}^{2}+\left(\mu_{X}+\mu_{Y}\right)^{2} \leq\left(\sigma_{Y}+\sigma_{X}\right)^{2}+\left(\mu_{X}+\mu_{Y}\right)^{2}, \text { if } \rho_{X Y} \leq 0, \tag{3.10}
\end{gather*}
$$

$$
\begin{gather*}
E\left[(X+Y)^{2}\right] \geq \sigma_{X}^{2}+\sigma_{Y}^{2}+\left(\mu_{X}+\mu_{Y}\right)^{2} \geq\left(\sigma_{X}-\sigma_{Y}\right)^{2}+\left(\mu_{X}+\mu_{Y}\right)^{2}, \text { if } \rho_{X Y} \geq 0,  \tag{3.11}\\
E\left[(Y+X)^{2}\right]=\sigma_{X}^{2}+\sigma_{Y}^{2}+\left(\mu_{X}+\mu_{Y}\right)^{2}, \text { if } \rho_{X Y}=0 \tag{3.12}
\end{gather*}
$$

From (3.1), it is also easy to see that

$$
\begin{equation*}
E\left[\left(\frac{Y}{\sigma_{Y}}-\frac{X}{\sigma_{X}}\right)^{2}\right]=2\left(1-\rho_{X Y}\right)+\left(\frac{\mu_{Y}}{\sigma_{Y}}-\frac{\mu_{X}}{\sigma_{X}}\right)^{2} . \tag{3.13}
\end{equation*}
$$

Let

$$
\begin{equation*}
\tilde{X}=\frac{X-\mu_{X}}{\sigma_{X}}, \quad \tilde{Y}=\frac{Y-\mu_{Y}}{\sigma_{Y}}, \quad \rho(\tilde{X}, \tilde{Y})=\rho(X, Y)=\rho_{X Y}, \tag{3.14}
\end{equation*}
$$

where we set $\tilde{X}=0$ if $\sigma_{X}=0$, and $\tilde{Y}=0$ if $\sigma_{Y}=0$. We then have:

$$
\begin{equation*}
E(\tilde{X})=E(\tilde{Y})=0, \quad \mathrm{~V}(\tilde{X})=\mathrm{V}(\tilde{Y})=1, \tag{3.15}
\end{equation*}
$$

and

$$
\begin{equation*}
E\left[(\tilde{Y}-\tilde{X})^{2}\right]=2\left(1-\rho_{X Y}\right) . \tag{3.16}
\end{equation*}
$$

Since

$$
\begin{equation*}
X=\mu_{X}+\sigma_{X} \tilde{X}, \quad Y=\mu_{Y}+\sigma_{Y} \tilde{Y} \tag{3.17}
\end{equation*}
$$

we get

$$
\begin{align*}
E\left[(Y-X)^{2}\right] & =E\left\{\left[\left(\mu_{Y}+\sigma_{Y} \tilde{Y}\right)-\left(\mu_{X}+\sigma_{X} \tilde{X}\right)\right]^{2}\right\} \\
& =E\left\{\left[\left(\sigma_{Y} \tilde{Y}-\sigma_{X} \tilde{X}\right)+\left(\mu_{Y}-\mu_{X}\right)\right]^{2}\right\} \\
& =E\left\{\left[\left(\sigma_{Y} \tilde{Y}-\sigma_{X} \tilde{X}\right)+\left(\mu_{Y}-\mu_{X}\right)\right]^{2}\right\} \\
& =E\left[\left(\sigma_{Y} \tilde{Y}-\sigma_{X} \tilde{X}\right)^{2}\right]+\left(\mu_{Y}-\mu_{X}\right)^{2} \tag{3.18}
\end{align*}
$$

hence

$$
\begin{align*}
E\left[(Y-X)^{2}\right] & =\sigma_{Y}^{2} E\left[\left(\tilde{Y}-\frac{\sigma_{X}}{\sigma_{Y}} \tilde{X}\right)^{2}\right]+\left(\mu_{Y}-\mu_{X}\right)^{2} \\
& =\sigma_{Y}^{2}\left[1+\left(\frac{\sigma_{X}}{\sigma_{Y}}\right)^{2}-2\left(\frac{\sigma_{X}}{\sigma_{Y}}\right) \rho_{X Y}\right]+\left(\mu_{Y}-\mu_{X}\right)^{2}, \quad \text { if } \sigma_{Y} \neq 0 \tag{3.19}
\end{align*}
$$

and

$$
\begin{equation*}
E\left[(Y-X)^{2}\right]=\sigma_{X}^{2}+\left(\mu_{Y}-\mu_{X}\right)^{2}, \quad \text { if } \sigma_{Y}=0 \tag{3.20}
\end{equation*}
$$

If the variances of $X$ and $Y$ are the same, i.e.

$$
\begin{equation*}
\sigma_{Y}^{2}=\sigma_{X}^{2} \tag{3.21}
\end{equation*}
$$

we have:

$$
\begin{align*}
E\left[(Y-X)^{2}\right] & =2 \sigma_{Y}^{2}\left(1-\rho_{X Y}\right)+\left(\mu_{Y}-\mu_{X}\right)^{2} \\
& =2 \sigma_{X}^{2}\left(1-\rho_{X Y}\right)+\left(\mu_{Y}-\mu_{X}\right)^{2} . \tag{3.22}
\end{align*}
$$

If the means and variances of $X$ and $Y$ are the same, i.e.

$$
\begin{equation*}
\mu_{Y}=\mu_{X} \text { and } \sigma_{Y}^{2}=\sigma_{X}^{2} \tag{3.23}
\end{equation*}
$$

we have:

$$
\begin{equation*}
E\left[(Y-X)^{2}\right]=2 \sigma_{Y}^{2}\left(1-\rho_{X Y}\right)=2 \sigma_{X}^{2}\left(1-\rho_{X Y}\right) \tag{3.24}
\end{equation*}
$$

and

$$
\begin{equation*}
0 \leq E\left[(Y-X)^{2}\right] \leq 4 \sigma_{X}^{2} \tag{3.25}
\end{equation*}
$$

so that

$$
\begin{equation*}
E\left[(Y-X)^{2}\right]=0 \text { and } \mathrm{P}[Y=X]=1, \text { if } \rho_{X Y}=1, \tag{3.26}
\end{equation*}
$$

and, using Chebyshev's inequality,

$$
\begin{align*}
& \mathrm{P}[|Y-X|>c] \leq \frac{E\left[(Y-X)^{2}\right]}{c^{2}}=\frac{2 \sigma_{X}^{2}\left(1-\rho_{X Y}\right)}{c^{2}} \text { for any } c>0,  \tag{3.27}\\
& \mathrm{P}\left[|Y-X|>c \sigma_{X}\right] \leq \frac{E\left[(Y-X)^{2}\right]}{\sigma_{X}^{2} c^{2}}=\frac{2\left(1-\rho_{X Y}\right)}{c^{2}} \text { for any } c>0 . \tag{3.28}
\end{align*}
$$

If $\mu_{Y}=\mu_{X}$ and $\sigma_{Y}^{2}=\sigma_{X}^{2}>0$, we also have:

$$
\begin{gather*}
E\left[(Y-X)^{2}\right]=0 \Leftrightarrow \rho_{X Y}=1,  \tag{3.29}\\
E\left[(Y-X)^{2}\right]=2 \sigma_{X}^{2} \Leftrightarrow \rho_{X Y}=0,  \tag{3.30}\\
E\left[(Y-X)^{2}\right]=4 \sigma_{X}^{2} \Leftrightarrow \rho_{X Y}=-1 . \tag{3.31}
\end{gather*}
$$

Since

$$
\begin{equation*}
\sigma_{Y}(\tilde{Y}-\tilde{X})=Y-\mu_{Y}-\frac{\sigma_{Y}}{\sigma_{X}}\left(X-\mu_{X}\right)=Y-\left(\mu_{Y}+\frac{\sigma_{Y}}{\sigma_{X}} \mu_{X}\right)-\frac{\sigma_{Y}}{\sigma_{X}} X, \tag{3.32}
\end{equation*}
$$

the linear function

$$
\begin{equation*}
L_{0}(X)=\left(\mu_{Y}+\frac{\sigma_{Y}}{\sigma_{X}} \mu_{X}\right)+\frac{\sigma_{Y}}{\sigma_{X}} X \tag{3.33}
\end{equation*}
$$

can be viewed as a "forecast" of $Y$ based on $X$ such that

$$
\begin{equation*}
E\left[\left(Y-L_{0}(X)\right)^{2}\right]=\sigma_{Y}^{2} E\left[(\tilde{Y}-\tilde{X})^{2}\right]=2 \sigma_{Y}^{2}\left(1-\rho_{X Y}\right) \tag{3.34}
\end{equation*}
$$

It is then of interest to note that

$$
\begin{equation*}
E\left[\left(Y-L_{0}(X)\right)^{2}\right] \leq E\left[\left(Y-\mu_{Y}\right)^{2}\right]=\sigma_{Y}^{2} \Leftrightarrow \rho_{X Y} \geq 0.5, \tag{3.35}
\end{equation*}
$$

with

$$
\begin{equation*}
E\left[\left(Y-L_{0}(X)\right)^{2}\right]<E\left[\left(Y-\mu_{Y}\right)^{2}\right]=\sigma_{Y}^{2} \Leftrightarrow \rho_{X Y}>0.5 \tag{3.36}
\end{equation*}
$$

when $\sigma_{Y}^{2}>0$. Thus $L_{0}(X)$ provides a "better forecast" of $Y$ than the mean of $Y$, when $\rho_{X Y}>0.5$. If $\rho_{X Y}<0.5$ and $\sigma_{Y}^{2}>0$, the opposite holds: $E\left[\left(Y-L_{0}(X)\right)^{2}\right]>\sigma_{Y}^{2}$.

### 3.2. Polarization identity

Since

$$
\begin{align*}
& V(X+Y)=V(X)+V(Y)+2 C(X, Y),  \tag{3.37}\\
& V(X-Y)=V(X)+V(Y)-2 C(X, Y), \tag{3.38}
\end{align*}
$$

it is easy to see that

$$
\begin{equation*}
C(X, Y)=\frac{1}{4}[V(X+Y)-V(X-Y)] . \tag{3.39}
\end{equation*}
$$

(3.39) is sometimes called the "polarization identity". Further,

$$
\begin{equation*}
\rho(X, Y)=\frac{1}{4} \frac{V(X+Y)-V(X-Y)}{\sigma_{X} \sigma_{Y}}=\frac{1}{4}\left[\frac{\sigma_{X+Y}^{2}}{\sigma_{X} \sigma_{Y}}-\frac{\sigma_{X-Y}^{2}}{\sigma_{X} \sigma_{Y}}\right] . \tag{3.40}
\end{equation*}
$$

On $X+Y$ and $X-Y$, it also interesting to observe that

$$
\begin{equation*}
C(X+Y, X-Y)=[V(X)-V(Y)]+[C(Y, X)-C(X, Y)]=V(X)-V(Y) \tag{3.41}
\end{equation*}
$$

so

$$
\begin{equation*}
C((X+Y) / 2, X-Y)=C(X+Y, X-Y)=0, \quad \text { if } V(X)=V(Y) . \tag{3.42}
\end{equation*}
$$

This holds irrespective of the covariance between between $X$ and $Y$. In particular, if the vector ( $X, Y$ ) is multinormal $X+Y$ and $X-Y$ are independent when $V(X)=V(Y)$.

## 4. Covariance matrices

Consider now kr.v.'s $X_{1}, X_{2}, \ldots, X_{k}$ such that

$$
\begin{aligned}
\mathrm{E}\left(X_{i}\right) & =\mu_{i}, i=1, \ldots, k \\
\mathrm{C}\left(X_{i}, X_{j}\right) & =\sigma_{i j}, i, j=1, \ldots, k
\end{aligned}
$$

We often wish to compute the mean and variance of a linear combination of $X_{1}, \ldots, X_{k}$ :

$$
\Sigma_{i=1}^{k} a_{i} X_{i}=a_{1} X_{1}+a_{2} X_{2}+\cdots+a_{k} X_{k} .
$$

It is easily verified that

$$
\mathrm{E}\left[\Sigma_{i=1}^{k} a_{i} X_{i}\right]=\Sigma_{i=1}^{k} a_{i} \mu_{i}
$$

and

$$
\begin{aligned}
\mathrm{V}\left[\Sigma_{i=1}^{k} a_{i} X_{i}\right] & =\mathrm{E}\left\{\left[\Sigma_{i=1}^{k} a_{i}\left(X_{i}-\mu_{i}\right)\right]\left[\Sigma_{j=1}^{k} a_{j}\left(X_{j}-\mu_{j}\right)\right]\right\} \\
& =\Sigma_{i=1}^{k} \Sigma_{j=1}^{k} a_{i} a_{j} \sigma_{i j} .
\end{aligned}
$$

Since such formulae may often become cumbersome, it will be convenient to use vector and matrix notation

We define a random vector $\mathbf{X}$ and its mean value $\mathrm{E}(\mathbf{X})$ by:

$$
\mathbf{X}=\left(\begin{array}{c}
X_{1} \\
\vdots \\
X_{k}
\end{array}\right) \quad, \mathrm{E}(\mathbf{X})=\left(\begin{array}{c}
\mathrm{E}\left(X_{1}\right) \\
\vdots \\
\mathrm{E}\left(X_{k}\right)
\end{array}\right)=\left(\begin{array}{c}
\mu_{1} \\
\vdots \\
\mu_{k}
\end{array}\right) \equiv \mu_{X}
$$

Similarly, we define a random matrix $M$ and its mean value $\mathrm{E}(M)$ by:

$$
M=\left[\begin{array}{cccc}
X_{11} & X_{12} & \ldots & X_{1 n} \\
X_{21} & X_{22} & \ldots & X_{2 n} \\
\vdots & \vdots & & \vdots \\
X_{m 1} & X_{m 2} & \ldots & X_{m n}
\end{array}\right], \mathrm{E}(M)=\left[\begin{array}{cccc}
\mathrm{E}\left(X_{11}\right) & \mathrm{E}\left(X_{12}\right) & \ldots & \mathrm{E}\left(X_{1 n}\right) \\
\mathrm{E}\left(X_{21}\right) & \mathrm{E}\left(X_{22}\right) & \ldots & \mathrm{E}\left(X_{2 n}\right) \\
\vdots & \vdots & & \vdots \\
\mathrm{E}\left(X_{m 1}\right) & \mathrm{E}\left(X_{m 2}\right) & \ldots & \mathrm{E}\left(X_{m n}\right)
\end{array}\right]
$$

where the $X_{i j}$ are r.v.'s. To a random vector $\mathbf{X}$, we can associate a covariance matrix $\vee(\mathbf{X})$ :

$$
\begin{aligned}
\mathrm{V}(\mathbf{X}) & =\mathrm{E}\left\{[\mathbf{X}-\mathrm{E}(\mathbf{X})][\mathbf{X}-\mathrm{E}(\mathbf{X})]^{\prime}\right\}=\mathrm{E}\left\{\left[\mathbf{X}-\mu_{X}\right]\left[\mathbf{X}-\mu_{X}\right]^{\prime}\right\} \\
& =\mathrm{E}\left\{\left[\begin{array}{cccc}
\left(X_{1}-\mu_{1}\right)\left(X_{1}-\mu_{1}\right) & \left(X_{1}-\mu_{1}\right)\left(X_{2}-\mu_{2}\right) & \ldots & \left(X_{1}-\mu_{1}\right)\left(X_{k}-\mu_{k}\right) \\
\vdots & \vdots & \vdots \\
\left(X_{k}-\mu_{k}\right)\left(X_{1}-\mu_{1}\right) & \left(X_{k}-\mu_{k}\right)\left(X_{2}-\mu_{2}\right) & \ldots & \left(X_{k}-\mu_{k}\right)\left(X_{k}-\mu_{k}\right)
\end{array}\right]\right\} \\
& =\left[\begin{array}{cccc}
\sigma_{11} & \sigma_{12} & \ldots & \sigma_{1 k} \\
\vdots & \vdots & \vdots \\
\sigma_{k 1} & \sigma_{k 2} & \ldots & \sigma_{k k}
\end{array}\right]=\Sigma .
\end{aligned}
$$

If $\mathbf{a}=\left(a_{1}, \ldots, a_{k}\right)^{\prime}$, we see that:

$$
\Sigma_{i=1}^{k} a_{i} X_{i}=\mathbf{a}^{\prime} \mathbf{X}
$$

Basic properties of $\mathrm{E}(\mathbf{X})$ and $\mathrm{V}(\mathbf{X})$ are summarized by the following proposition.
4.1 Proposition Let $\mathbf{X}=\left(X_{1}, \ldots, X_{k}\right)^{\prime}$ a $k \times 1$ random vector, $\alpha$ a scalar, a and $\mathbf{b}$ fixed $k \times 1$ vectors, and $A$ a fixed $g \times k$ matrix. Then, provided the moments considered are finite, we have the following properties:
(a) $\mathrm{E}(\mathbf{X}+\mathbf{a})=\mathrm{E}(\mathbf{X})+\mathbf{a}$;
(b) $\mathrm{E}(\alpha \mathbf{X})=\alpha \mathrm{E}(\mathbf{X})$;
(c) $\mathrm{E}\left(\mathbf{a}^{\prime} \mathbf{X}\right)=\mathbf{a}^{\prime} \mathrm{E}(\mathbf{X}), \mathrm{E}(A \mathbf{X})=A \mathrm{E}(\mathbf{X})$;
(d) $\mathrm{V}(\mathbf{X}+\mathbf{a})=\mathrm{V}(\mathbf{X})$;
(e) $\vee(\alpha \mathbf{X})=\alpha^{2} \vee(\mathbf{X})$;
(f) $\vee\left(\mathbf{a}^{\prime} \mathbf{X}\right)=\mathbf{a}^{\prime} \vee(\mathbf{X}) \mathbf{a}, \vee(A \mathbf{X})=A \vee(\mathbf{X}) A^{\prime}$;
(g) $\mathrm{C}\left(\mathbf{a}^{\prime} \mathbf{X}, \mathbf{b}^{\prime} \mathbf{X}\right)=\mathbf{a}^{\prime} \vee(\mathbf{X}) \mathbf{b}=\mathbf{b}^{\prime} \vee(\mathbf{X}) \mathbf{a}$.
4.2 Theorem Let $\mathbf{X}=\left(X_{1}, \ldots, X_{k}\right)^{\prime}$ be a random vector with covariance matrix $\vee(\mathbf{X})=\Sigma$. Then we have the following properties:
(a) $\Sigma^{\prime}=\Sigma$;
(b) $\Sigma$ is a positive semidefinite matrix;
(c) $0 \leq|\Sigma| \leq \sigma_{1}^{2} \sigma_{2}^{2} \ldots \sigma_{k}^{2}$ where $\sigma_{i}^{2}=\mathrm{V}\left(X_{i}\right), i=1, \ldots, k$;
(d) $|\Sigma|=0 \Leftrightarrow$ there is at least one linear relation between the r.v.'s $X_{1}, \ldots, X_{k}$, i.e., we can find constants $a_{1}, \ldots, a_{k}, b$ not all equal to zero such that $a_{1} X_{1}+\cdots+a_{k} X_{k}=b$ with probability 1 ;
(e) $\operatorname{rank}(\Sigma)=r<k \Leftrightarrow \mathbf{X}$ can be expressed in the form

$$
\mathbf{X}=B \mathbf{Y}+\mathbf{c}
$$

where $\mathbf{Y}$ is a random vector of dimension $r$ whose covariance matrix is $I_{r}, B$ is a $k \times r$ matrix of rank $r$, and $\mathbf{c}$ is a $k \times 1$ constant vector.
4.3 Remark We call the determinant $|\Sigma|$ the generalized variance of $\mathbf{X}$.
4.4 Definition If we consider two random vectors $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ with dimensions $k_{1} \times 1$ and $k_{2} \times 1$ respectively, the covariance matrix between $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ is defined by:

$$
\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)=\mathrm{E}\left\{\left[\mathbf{x}_{1}-\mathrm{E}\left(\mathbf{X}_{1}\right)\right]\left[\mathbf{X}_{2}-\mathrm{E}\left(\mathbf{X}_{2}\right)\right]^{\prime}\right\}
$$

The following proposition summarizes some basic properties of $\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)$.
4.5 Proposition Let $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ two random vectors of dimensions $k_{1} \times 1$ and $k_{2} \times 1$ respectively. Then, provided the moments considered are finite we have the following properties:
(a) $\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)=\mathrm{E}\left[\mathbf{X}_{1} \mathbf{X}_{2}^{\prime}\right]-\mathrm{E}\left(\mathbf{X}_{1}\right) \mathrm{E}\left(\mathbf{X}_{2}\right)^{\prime}$;
(b) $\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)=\mathrm{C}\left(\mathbf{X}_{2}, \mathbf{X}_{1}\right)^{\prime}$;
(c) $\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{1}\right)=\mathrm{V}\left(\mathbf{X}_{1}\right), \mathrm{C}\left(\mathbf{X}_{2}, \mathbf{X}_{2}\right)=\mathrm{V}\left(\mathbf{X}_{2}\right)$;
(d) if $\mathbf{a}$ and $\mathbf{b}$ are fixed vectors of dimensions $k_{1} \times 1$ and $k_{2} \times 1$ respectively,

$$
\mathrm{C}\left(\mathbf{X}_{1}+\mathbf{a}, \mathbf{X}_{2}+\mathbf{b}\right)=\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right) ;
$$

(e) if $\alpha$ and $\beta$ are two scalar constants,

$$
\mathrm{C}\left(\alpha \mathbf{X}_{1}, \beta \mathbf{X}_{2}\right)=\alpha \beta \mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right) ;
$$

$(f)$ if $\mathbf{a}$ and $\mathbf{b}$ are fixed $k_{1} \times 1$ and $k_{2} \times 1$ vectors,

$$
\mathrm{C}\left(\mathbf{a}^{\prime} \mathbf{X}_{1}, \mathbf{b}^{\prime} \mathbf{X}_{2}\right)=\mathbf{a}^{\prime} \mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right) \mathbf{b} ;
$$

$(g)$ if $A$ and $B$ are fixed matrices matrices with dimensions $g_{1} \times k_{1}$ and $g_{2} \times k_{2}$ respectively,

$$
\mathrm{C}\left(A \mathbf{X}_{1}, B \mathbf{X}_{2}\right)=\mathbf{A C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right) \mathbf{B}^{\prime} ;
$$

(h) if $k_{1}=k_{2}$ and $\mathbf{X}_{3}$ is a $k \times 1$ random vector,

$$
\mathrm{C}\left(\mathbf{X}_{1}+\mathbf{X}_{2}, \mathbf{X}_{3}\right)=\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{x}_{3}\right)+\mathrm{C}\left(\mathbf{X}_{2}, \mathbf{X}_{3}\right) ;
$$

(i) if $k_{1}=k_{2}$,

$$
\begin{aligned}
\mathrm{V}\left(\mathbf{X}_{1}+\mathbf{X}_{2}\right) & =\mathrm{V}\left(\mathbf{x}_{1}\right)+\mathrm{V}\left(\mathbf{X}_{2}\right)+\mathrm{C}\left(\mathbf{x}_{1}, \mathbf{x}_{2}\right)+\mathrm{C}\left(\mathbf{x}_{2}, \mathbf{X}_{1}\right), \\
\mathrm{V}\left(\mathbf{x}_{1}-\mathbf{X}_{2}\right) & =\mathrm{V}\left(\mathbf{x}_{1}\right)+\mathrm{V}\left(\mathbf{X}_{2}\right)-\mathrm{C}\left(\mathbf{x}_{1}, \mathbf{x}_{2}\right)-\mathrm{C}\left(\mathbf{x}_{2}, \mathbf{x}_{1}\right) .
\end{aligned}
$$


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